The multicanonical MC algorithm samples configurations with the weight

$$\mathcal{P}_L^{\text{MC}}(S) \sim e^{(\alpha_L^k + \beta_L^k S)} \text{ for } S_L^k < S \le S_L^{k+1}$$
 (7)

instead of sampling with the usual Boltzmann factor  $P_L^B(S) \sim \exp(\beta_L^c S)$  corresponding to the canonical ensemble. Here we partitioned the total action interval 0  $\leq S \leq 2V$  into k = 0, ..., N (N+1 odd) intervals  $I_k$  $=(S_L^k, S_L^{k+1}]$ . The idea of the multicanonical MC algorithm is to choose intervals  $I_k$  and values of  $\beta_L^k$  and  $\alpha_L^k$  at the pseudocritical point  $\beta_L^c$  in such a way that the resulting multicanonical action density  $\mathcal{P}_L(S)$  has an approximately flat behavior for values of the action in the interval  $[S_L^{1,\text{max}}, S_L^{2,\text{max}}]$ ; that is to say, configurations dominated by the interface are no longer exponentially suppressed