## Rotational Dynamics - 1

Bicycle (1):  $\omega = \frac{v}{r} \operatorname{rad}, \quad T = \frac{2\pi \operatorname{rad}}{\omega}.$ 

Belt Drive (2): Use relation of frequencies

$$f_{a} r_{a} = f_{c} r_{c} , \quad \omega_{a} = 2\pi f_{a} \operatorname{rad}/\operatorname{rev}, \quad \alpha_{a} t = \omega_{a} .$$

Spinning Wheel and Arrow (3). Times have to agree:

$$\frac{L_{\rm arrow}}{v_{\rm arrow}} = \frac{L_{\rm wheel}}{v_{\rm wheel}}\,,\quad L_{\rm wheel} = \frac{R}{8}$$

Cyclist (4).

$$\theta = \alpha \, \frac{t^2}{2} \,, \quad \omega = \alpha \, t \,, \quad d = \theta \, r/\mathrm{rad} \,.$$

## Rotational Dynamics - 2

**Rotational Variables (5).** Use just numbers. Fix units on output. Given is  $\theta(t)$ . Then

$$\omega(t) = \frac{d\theta}{dt}, \quad \alpha = \frac{d\omega}{dt}, \quad \overline{\alpha} = \frac{\omega_2 - \omega_2}{t_2 - t_1}.$$

Crumb on rotating table (6):

$$T = \frac{\operatorname{rev}}{f}, \quad v = \frac{2\pi r}{T}, \quad a = ?$$

Torque on a Door (7):

 $\tau = r F \sin(\theta).$