

Electrodynamics A (PHY 5346) Fall 2016 Solutions

Set 3:

- (7) Exercise (CW 5 points): Lorentz group Lie matrix generator.

The Matrix L is:

$$L = \begin{pmatrix} l_0^0 & l_0^1 & l_0^2 & l_0^3 \\ l_1^0 & l_1^1 & l_1^2 & l_1^3 \\ l_2^0 & l_2^1 & l_2^2 & l_2^3 \\ l_3^0 & l_3^1 & l_3^2 & l_3^3 \end{pmatrix}.$$

- (1) The matrix g is:

$$g = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}.$$

By matrix multiplication:

$$-gL = \begin{pmatrix} -l_0^0 & -l_0^1 & -l_0^2 & -l_0^3 \\ l_1^0 & l_1^1 & l_1^2 & l_1^3 \\ l_2^0 & l_2^1 & l_2^2 & l_2^3 \\ l_3^0 & l_3^1 & l_3^2 & l_3^3 \end{pmatrix}.$$

- (2) The transpose of L is:

$$\tilde{L} = \begin{pmatrix} \tilde{l}_0^0 & \tilde{l}_0^1 & \tilde{l}_0^2 & \tilde{l}_0^3 \\ \tilde{l}_1^0 & \tilde{l}_1^1 & \tilde{l}_1^2 & \tilde{l}_1^3 \\ \tilde{l}_2^0 & \tilde{l}_2^1 & \tilde{l}_2^2 & \tilde{l}_2^3 \\ \tilde{l}_3^0 & \tilde{l}_3^1 & \tilde{l}_3^2 & \tilde{l}_3^3 \end{pmatrix} = \begin{pmatrix} l_0^0 & l_1^0 & l_2^0 & l_3^0 \\ l_1^1 & l_1^1 & l_2^1 & l_3^1 \\ l_2^2 & l_2^1 & l_2^2 & l_3^2 \\ l_3^3 & l_3^1 & l_3^2 & l_3^3 \end{pmatrix}.$$

- (3) By matrix multiplication:

$$\tilde{L}g = \begin{pmatrix} l_0^0 & -l_1^0 & -l_2^0 & -l_3^0 \\ l_1^0 & -l_1^1 & -l_2^1 & -l_3^1 \\ l_2^0 & -l_2^1 & -l_2^2 & -l_3^2 \\ l_3^0 & -l_3^1 & -l_3^2 & -l_3^3 \end{pmatrix}.$$

(4) Set $-gL = \tilde{L}g$ and compare the components:

$$\begin{pmatrix} -l_0^0 = l_0^0 & -l_1^0 = -l_1^0 & -l_2^0 = -l_2^0 & -l_3^0 = -l_3^0 \\ l_0^1 = l_1^0 & l_1^1 = -l_1^1 & l_2^1 = -l_2^1 & l_3^1 = -l_3^1 \\ l_0^2 = l_2^0 & l_1^2 = -l_2^1 & l_2^2 = -l_2^2 & l_3^2 = -l_3^2 \\ l_0^3 = l_3^0 & l_1^3 = -l_3^1 & l_2^3 = -l_3^2 & l_3^3 = -l_3^3 \end{pmatrix}.$$

The resulting matrix is:

$$\begin{pmatrix} 0 & l_1^0 & l_2^0 & l_3^0 \\ l_1^0 & 0 & l_2^1 & l_3^1 \\ l_2^0 & -l_2^1 & 0 & l_3^2 \\ l_3^0 & -l_3^1 & -l_3^2 & 0 \end{pmatrix}.$$

- (8) Exercise (5 points): Obtain the result of the previous Exercise discussing the elements of $g^{\alpha\beta} \tilde{l}_\beta^\gamma g_{\gamma\delta} = -l_\delta^\alpha$. Performing the contractions we get $\tilde{l}_\delta^\alpha = -l_\delta^\alpha$. Using now the definition $\tilde{l}_\delta^\alpha = l_\delta^\alpha$, the following equations are obtained (no summations, $a = 0, 1, 2, 3$, $i = 1, 2, 3$ and $j = 1, 2, 3$):

$$\tilde{l}_a^a = l_a^a = +l_a^a \Rightarrow l_a^a = -l_a^a = 0,$$

$$\tilde{l}_0^i = l_0^i = -l_i^0 \Rightarrow l_i^0 = +l_0^i,$$

$$\tilde{l}_j^i = l_j^i = +l_i^j \Rightarrow l_i^j = -l_j^i$$

and the resulting matrix is the same as before.

- (9) Exercise: A rotation and a boost generator.

For S_3 we have

$$S_3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \text{and} \quad (S_3)^2 = -\mathbf{1}_{2,3} \quad \text{with} \quad \mathbf{1}_{2,3} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Therefore, for $n = 1, 2, 3, \dots$

$$(S_3)^{2n} = (-1)^n \mathbf{1}_{2,3} \quad \text{and} \quad (S_3)^{2n+1} = (-1)^n S_3$$

and the result follows:

$$\begin{aligned} e^{-\omega S_3} &= \mathbf{1} + \sum_{n=1}^{\infty} (-1)^n \frac{\omega^{2n}}{(2n)!} \mathbf{1}_{2,3} - \sum_{n=0}^{\infty} (-1)^n \frac{\omega^{2n+1}}{(2n+1)!} S_3 \\ &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \omega & \sin \omega & 0 \\ 0 & -\sin \omega & \cos \omega & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}. \end{aligned}$$

Similarly we deal with K_1 :

$$K_1 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \text{and} \quad (K_1)^2 = \mathbf{1}_{1,2} \quad \text{with} \quad \mathbf{1}_{1,2} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Therefore, for $n = 1, 2, 3, \dots$

$$(K_1)^{2n} = \mathbf{1}_{1,2} \quad \text{and} \quad (K_1)^{2n+1} = K_1$$

and

$$e^{-\zeta K_1} = \mathbf{1} + \sum_{n=1}^{\infty} \frac{\omega^{2n}}{(2n)!} \mathbf{1}_{1,2} - \sum_{n=0}^{\infty} \frac{\omega^{2n+1}}{(2n+1)!} K_1 = \begin{pmatrix} \cosh \zeta & -\sinh \zeta & 0 & 0 \\ -\sinh \zeta & \cosh \zeta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

(10) Exercise: Four-dimensional Levi-Civita tensor.

(1) Using the Einstein summation convention of the left-hand side, but not on the right-hand side, of the following equation we have

$$g_{\alpha_1 \alpha_2} g_{\beta_1 \beta_2} g_{\gamma_1 \gamma_2} g_{\delta_1 \delta_2} \epsilon^{\alpha_2 \beta_2 \gamma_2 \delta_2} = g_{\alpha_1 \alpha_1} g_{\beta_1 \beta_1} g_{\gamma_1 \gamma_1} g_{\delta_1 \delta_1} \epsilon^{\alpha_1 \beta_1 \gamma_1 \delta_1}.$$

The right-hand side is zero unless $\alpha_1 \beta_1 \gamma_1 \delta_1$ are a permutation $\pi_0 \pi_1 \pi_2 \pi_3$ of the numbers 0, 1, 2, 3 and in that case

$$\epsilon_{\pi_0 \pi_1 \pi_2 \pi_3} = g_{\pi_0 \pi_0} g_{\pi_1 \pi_1} g_{\pi_2 \pi_2} g_{\pi_3 \pi_3} \epsilon^{\pi_0 \pi_1 \pi_2 \pi_3} = (-1)^3 \epsilon^{\pi_0 \pi_1 \pi_2 \pi_3},$$

which proves $\epsilon_{\alpha \beta \gamma \delta} = -\epsilon^{\alpha \beta \gamma \delta}$.

(2) We have $\epsilon_{\alpha \beta \gamma_1 \delta_1} \epsilon^{\alpha \beta \gamma_2 \delta_2} = 0$ unless either $\gamma_1 = \gamma_2$, $\delta_1 = \delta_2$ or $\gamma_1 = \delta_2$, $\delta_1 = \gamma_2$ or (otherwise one of the already used numbers will be repeated by α or β of the sums). Therefore,

$$\epsilon_{\alpha \beta \gamma_1 \delta_1} \epsilon^{\alpha \beta \gamma_2 \delta_2} = a \delta_{\gamma_1}^{\gamma_2} \delta_{\delta_1}^{\delta_2} + b \delta_{\gamma_1}^{\delta_2} \delta_{\delta_1}^{\gamma_2}$$

holds. With no summation in the permutation indices π_0 to π_3 the constants follow from

$$\begin{aligned}\epsilon_{\alpha\beta\pi_2\pi_3}\epsilon^{\alpha\beta\pi_2\pi_3} &= \epsilon_{\pi_0\pi_1\pi_2\pi_3}\epsilon^{\pi_0\pi_1\pi_2\pi_3} + \epsilon_{\pi_1\pi_0\pi_2\pi_3}\epsilon^{\pi_1\pi_0\pi_2\pi_3} = -2 = a, \\ \epsilon_{\alpha\beta\pi_2\pi_3}\epsilon^{\alpha\beta\pi_3\pi_2} &= \epsilon_{\pi_0\pi_1\pi_2\pi_3}\epsilon^{\pi_0\pi_1\pi_3\pi_2} + \epsilon_{\pi_1\pi_0\pi_2\pi_3}\epsilon^{\pi_1\pi_0\pi_3\pi_2} = +2 = b.\end{aligned}$$

(3) We have $\epsilon_{\alpha\beta_1\gamma_1\delta_1}\epsilon^{\alpha\beta_2\gamma_2\delta_2} = 0$ unless $\beta_2\gamma_2\delta_2$ is a permutation of $\beta_1\gamma_1\delta_1$. There are six such permutations, so that the results is a sum of the form

$$\begin{aligned}\epsilon_{\alpha\beta_1\gamma_1\delta_1}\epsilon^{\alpha\beta_2\gamma_2\delta_2} &= a_1\delta_{\beta_1}^{\beta_2}\delta_{\gamma_1}^{\gamma_2}\delta_{\delta_1}^{\delta_2} + a_2\delta_{\beta_1}^{\gamma_2}\delta_{\gamma_1}^{\delta_2}\delta_{\delta_1}^{\beta_2} + a_3\delta_{\beta_1}^{\delta_2}\delta_{\gamma_1}^{\beta_2}\delta_{\delta_1}^{\gamma_2} \\ &\quad + b_1\delta_{\beta_1}^{\beta_2}\delta_{\gamma_1}^{\delta_2}\delta_{\delta_1}^{\gamma_2} + b_2\delta_{\beta_1}^{\delta_2}\delta_{\gamma_1}^{\gamma_2}\delta_{\delta_1}^{\beta_2} + b_3\delta_{\beta_1}^{\gamma_2}\delta_{\gamma_1}^{\beta_2}\delta_{\delta_1}^{\delta_2},\end{aligned}$$

where it follows from (no summation) $\epsilon_{\pi_0\pi_1\pi_2\pi_3}\epsilon^{\pi_0\pi_1\pi_2\pi_3} = -1$ that $a_i = -1$ and $b_i = 1$ holds for $i = 1, 2, 3$.

(11) Exercise: Addition theorem for transverse velocity components.

In K' the motion with velocity \vec{u}' is

$$x'^i = c^{-1} u'^i x'^0.$$

With respect to frame K the origin of K' frame moves with speed v along the x^1 axis of K . For $i = 2, 3$ the Lorentz transformations give then

$$x^i = x'^i = c^{-1} u'^i \gamma (x^0 - \beta x^1).$$

Dividing by x^0 gives the velocity components in K :

$$c^{-1} u^i = c^{-1} u'^i \gamma (1 - \beta c^{-1} u^1) = c^{-1} u'^i \gamma \left(1 - \beta c^{-1} \frac{u'^1 + v}{1 + u'^1 v / c^2} \right),$$

where in the second step the already calculated equation for u^1 has been inserted. Bringing everything to the common denominator gives

$$\begin{aligned}u^i &= u'^i \gamma \frac{(1 + \beta u'^1 / c) - \beta c^{-1} (u'^1 + v)}{1 + u'^1 v / c^2} \\ &= u'^i \gamma \frac{1 - \beta^2}{1 + u'^1 v / c^2} = \frac{u'^i}{\gamma (1 + u'^1 v / c^2)},\end{aligned}$$

where $1 - \beta^2 = 1/\gamma^2$ was used in the last step.