

Definition

p. 47-53

Curl ①

$$\vec{\nabla} \times \vec{V} = \varepsilon_{ijk} \hat{x}_i \frac{\partial}{\partial x_j} V_k = \begin{vmatrix} \hat{x}_1 & \hat{x}_2 & \hat{x}_3 \\ \partial_1 & \partial_2 & \partial_3 \\ V_1 & V_2 & V_3 \end{vmatrix}$$

$$\partial_i = \frac{\partial}{\partial x_i}$$

Product Rule:

$$\vec{\nabla} \times (f \vec{V}) = f \vec{\nabla} \times \vec{V} + (\vec{\nabla} f) \times \vec{V}$$

Examples: $\vec{\nabla} \times \vec{r} = \varepsilon_{ijk} \hat{x}_i \frac{\partial}{\partial x_j} x_k$

$$= \varepsilon_{ijk} \hat{x}_i \delta_{jk} = \varepsilon_{iji} \hat{x}_i = \underline{\underline{0}}$$

$$\nabla \times (\vec{r} f(r)) = f(r) \underbrace{\vec{\nabla} \times \vec{r}}_0 + (\vec{\nabla} f) \times \vec{r}$$

$$= \frac{df}{dr} \vec{r} \times \vec{r} = \underline{\underline{0}}$$

Curl of a ~~the~~ gradient:

$$\vec{\nabla} \times (\vec{\nabla} \cdot \phi) = \varepsilon_{ijk} \hat{x}_i \frac{\partial}{\partial x_j} \left(\frac{\partial \phi}{\partial x_k} \right)$$

$$= \epsilon_{ijk} \hat{x}_i \frac{\partial}{\partial x_k} \frac{\partial \phi}{\partial x_j} = -\epsilon_{ikj} \frac{\partial}{\partial x_k} \frac{\partial \phi}{\partial x_j}$$

$$= -\epsilon_{ijk} \hat{x}_i \frac{\partial}{\partial x_j} \frac{\partial \phi}{\partial x_k} = -\vec{\nabla} \times (\vec{\nabla} \cdot \phi)$$

$$\Rightarrow \underline{\underline{\vec{\nabla} \times (\nabla \phi) = 0}}$$

General:

$$A_{ij} = -A_{ji}$$

$$S_{ij} = S_{ji}$$

$$A_{ij} S_{ij} = 0$$

Vector identities:

$$\nabla \times (\vec{A} \times \vec{B}) = \epsilon_{ijk} \hat{x}_i \frac{\partial}{\partial x_j} \epsilon_{klm} A_l B_m$$

$$= (\delta_{ix} \delta_{jm} - \delta_{im} \delta_{jx}) \hat{x}_i \frac{\partial}{\partial x_j} A_l B_m$$

$$= \hat{x}_i \frac{\partial}{\partial x_i} A_j B_j - \hat{x}_i \frac{\partial}{\partial x_j} A_j B_i$$

$$= \hat{x}_i \left(\frac{\partial A_i}{\partial x_i} \right) B_i + \hat{x}_i A_i \left(\frac{\partial B_i}{\partial x_i} \right)$$

$$- \hat{x}_i \left(\frac{\partial A_j}{\partial x_j} \right) B_i - \hat{x}_i A_j \left(\frac{\partial B_i}{\partial x_j} \right)$$

$$= (\vec{B} \cdot \vec{\nabla}) \vec{A} + \vec{A} (\nabla \cdot \vec{B}) - \vec{B} (\nabla \cdot \vec{A}) - (\vec{A} \cdot \vec{\nabla}) \vec{B}$$

book p.52
(1.7.5)

→ QM angular momentum operators:

$$\vec{L} = \vec{r} \times \vec{p}, \quad \vec{p} = -i \vec{\nabla}$$

$$L_i = -i \epsilon_{ijk} (x_j \frac{\partial}{\partial x_k})$$

$$L_1 = -i (x_2 \frac{\partial}{\partial x_3} - x_3 \frac{\partial}{\partial x_2})$$

$$L_2 = -i (x_3 \frac{\partial}{\partial x_1} - x_1 \frac{\partial}{\partial x_3})$$

$$L_3 = -i (x_1 \frac{\partial}{\partial x_2} - x_2 \frac{\partial}{\partial x_1})$$

Circulation (show figure):

Curl (4)

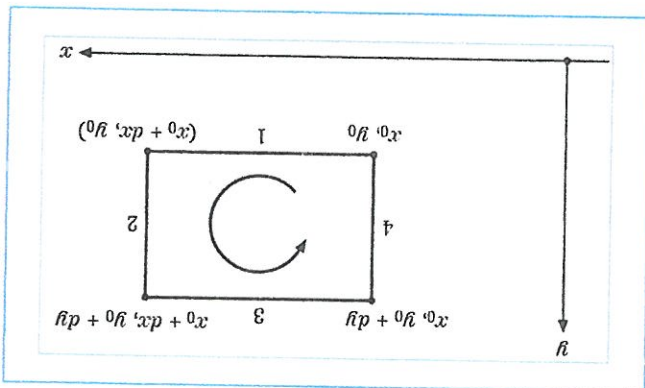
$$\left. \begin{aligned} (1) & V_x(x_0 + \frac{dx}{2}, y_0) dx \\ (3) & - V_x(x_0 + \frac{dx}{2}, y_0 + dy) dx \end{aligned} \right\} - \frac{\partial V_x}{\partial y} dx dy$$

$$\left. \begin{aligned} (2) & V_y(x_0 + dx, y_0 + \frac{dy}{2}) dy \\ (4) & - V_y(x_0, y_0 + \frac{dy}{2}) dy \end{aligned} \right\} + \frac{\partial V_y}{\partial x} dx dy$$

$$\text{Circulation}_{1234} = \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right) dx dy$$

$$\text{Circulation per unit area} = \nabla \times \vec{V} \Big|_z$$

In x-y plane



Circulation Around a Differential Loop

Figure 1.26

Successive Applications of ∇ : (Book 1.8 p.53)

(a) $\nabla \cdot \nabla \phi$, (b) $\nabla \times \nabla \phi = 0$ (done)

(c) $\nabla (\nabla \cdot \vec{V})$ (d) $\nabla \cdot (\nabla \times \vec{V})$

(e) $\nabla \times (\nabla \times \vec{V})$

$$\begin{aligned}
 (a) \quad \nabla \cdot \nabla \phi &= \sum_i \hat{x}_i \partial_i \cdot \sum_j \hat{x}_j \partial_j \phi \\
 &= \sum_i \sum_j \delta_{ij} \partial_i \partial_j \phi = \sum_i \partial_i^2 \phi \\
 &= \sum_i \frac{\partial^2 \phi}{\partial x_i^2} = \nabla^2 \phi
 \end{aligned}$$

Laplace Operator

Laplacian of a radial function: (p.54)

Product rule.

$$\begin{aligned}
 \nabla \cdot \nabla g(r) &= \nabla \cdot \left(\frac{1}{r} \frac{dg}{dr} \right) = \nabla \cdot \left(\frac{1}{r} \frac{dg}{dr} \right) \\
 &= (\nabla \cdot \frac{1}{r}) \frac{dg}{dr} + \frac{1}{r} (\nabla \cdot \frac{dg}{dr}) + \frac{1}{r} \nabla \cdot \frac{dg}{dr}
 \end{aligned}$$

(2)_a

$$= \frac{3}{r} \frac{dq}{dr} + \vec{r} \cdot \hat{r} \left(\frac{-1}{r^2} \right) \frac{d}{dr} + \frac{1}{r} \cdot \frac{1}{r} \frac{d^2 q}{dr^2}$$

$$= \frac{2}{r} \frac{dq}{dr} + \frac{d^2 q}{dr^2} \quad (\text{book 1.8.1})$$

(b) $\vec{\nabla} \times \vec{\nabla} \varphi = \epsilon_{ijk} x_i \partial_j \partial_k \varphi$
 (again) $= 0$

Because contraction of any asymmetric rank 2 line 2 indices tensor with a symmetric rank 2 tensor is zero:

$$A_{ij} = -A_{ji}, \quad S_{ij} = S_{ji}$$

$$\underline{A_{ij} S_{ij}} = -A_{ji} S_{ji} =$$

$$-A_{kl} S_{kl} = \underline{-A_{ij} S_{ij}}$$

→ (d) $\vec{\nabla} \cdot \vec{\nabla} \times \vec{V} = \partial_i \epsilon_{ijk} \partial_j V_k$ Backside

$$= \epsilon_{ijk} \partial_i \partial_j V_k = 0 \quad (\text{symmetric w. anti-symmetric})$$

Geometrical interpretation:

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Flow of curl through all surfaces adds to zero.

But, NO pairwise cancellation,

Flow through up-down surfaces (show figure):

$$\int_z \frac{\partial}{\partial z} \cdot \vec{\nabla} \times \vec{V} = \frac{\partial}{\partial z} \vec{\nabla} \times \vec{V} \Big|_z$$

$$= \frac{\partial}{\partial z} \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right) \neq 0$$

\vec{A} Vector potential

(3)

Example: $\vec{B} = \vec{\nabla} \times \vec{A}$ \vec{B} magnetic field

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \text{no magnetic monopoles.}$$

Relation between (a), (c) and (e): (Book 1.16/p.55)

$$\begin{aligned} \vec{\nabla} \times (\vec{\nabla} \times \vec{V}) &= \epsilon_{ijk} \epsilon_{klm} \hat{x}_i \partial_j \partial_l V_m \\ &= (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) \hat{x}_i \partial_j \partial_l V_m \end{aligned}$$

$$= \underbrace{\hat{x}_i \partial_j \partial_l V_m}_{\delta_{il} \delta_{jm}} - \underbrace{\hat{x}_i \partial_j \partial_l V_m}_{\delta_{im} \delta_{jl}}$$

$$= \vec{\nabla} (\vec{\nabla} \cdot \vec{V}) - \nabla^2 \vec{V}$$

Example: (Book 1.8.2, p.56)

Electromagnetic waves from Maxwell's equations in vacuum

$$\vec{\nabla} \cdot \vec{B} = 0, \quad \vec{\nabla} \cdot \vec{E} = 0 \quad (\text{no source})$$

$$\vec{\nabla} \times \vec{B} = \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}, \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

From displacement current

Induction

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = -\frac{d}{dt} \vec{\nabla} \times \vec{B}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E}) - \vec{\nabla}^2 \vec{E} = -\epsilon_0 \mu_0 \frac{d^2}{dt^2} \vec{E}$$

$$\vec{\nabla}^2 \vec{E} = -\frac{1}{c^2} \frac{d^2 \vec{E}}{dt^2} \quad \text{Wave equ.}$$

$$\Rightarrow \underline{\underline{c = \frac{1}{\sqrt{\epsilon_0 \mu_0}}}} \quad \text{Speed of light}$$

with ϵ_0, μ_0 known from electrostatics,

Unification of optics and electrodynamics,

Come back to partial differential eqns later.

> Addendum $\hat{x}_j \times \hat{x}_k = \epsilon_{ijk} \hat{x}_i$

Examples: $\hat{x}_1 \times \hat{x}_2 = \epsilon_{312} \hat{x}_3 = \hat{x}_3$
 $\hat{x}_2 \times \hat{x}_1 = \epsilon_{321} \hat{x}_3 = -\hat{x}_3$

$$\hat{x}_2 \times \hat{x}_3 = \epsilon_{123} \hat{x}_1 = \hat{x}_1$$

$$\hat{x}_3 \times \hat{x}_1 = \epsilon_{231} \hat{x}_2 = \hat{x}_2$$