

F ①

Final Review: δ_{ij} , $\vec{a} \cdot \vec{b}$

$$\epsilon_{i_1 \dots i_n} / \epsilon_{ijkl}$$

$$\vec{a} \times \vec{b}, \vec{a} \times (\vec{b} \times \vec{c}) \leftrightarrow \epsilon_{ijk} \epsilon_{lmk}$$

$$\vec{\nabla} = \sum_i \hat{x}_i \frac{\partial}{\partial x_i}, \quad \vec{\nabla} \phi, \quad \vec{\nabla} \cdot \vec{A} =$$

$$\vec{\nabla} \times \vec{A} =$$

Vector analysis:

Vector integration

Gauss' theorem:

V with closed surface

$$\int_V \vec{\nabla} \cdot \vec{A} \, d^3x = \oint_S \vec{A} \cdot d\vec{\tau}$$

Stoke's theorem: surface with boundary, C

$$\int_S (\nabla \times \vec{A}) \cdot d\vec{\tau} = \oint_C \vec{A} \cdot d\vec{s}$$

$$\vec{A} = u \vec{\nabla} v \quad (u, v \text{ scalar fcts}).$$

Green's identity

$$\oint_S u \vec{\nabla} v \cdot d\vec{\sigma} = \int_V d^3x [u \vec{\nabla}^2 v + (\vec{\nabla} u) \cdot (\vec{\nabla} v)]$$

||

$$\oint_S u \frac{\partial v}{\partial n} da \quad \left| \quad \begin{array}{l} u = v = U \\ u = \Phi_1 - \Phi_2, \quad \vec{\nabla}^2 U = 0 \end{array} \right.$$

$$\oint_S u \frac{\partial u}{\partial n} da = \int_V |\vec{\nabla} u|^2 d^3x$$

= 0 with Dirichlet BC $\Phi_2 = \Phi_1$ on S

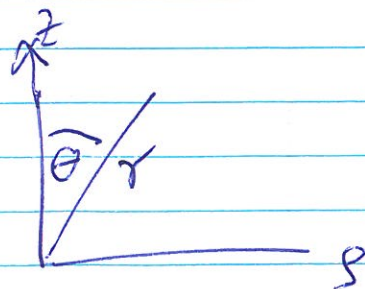
or Neumann BC $\frac{\partial \Phi_2}{\partial n} = \frac{\partial \Phi_1}{\partial n}$ on S .

Cylindrical Coordinates,

Spherical Coordinates:

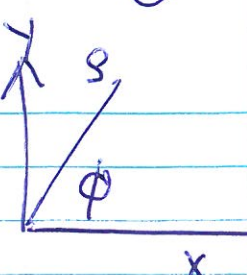
$$x_3 = z = r \cos \theta$$

$$\rho = r \sin \theta$$



F (3)

$$x_2 = y = s \sin \phi = r \sin \theta \sin \phi$$

$$x_1 = x = s \cos \phi = r \sin \theta \cos \phi$$


$$d\vec{s} = \hat{r} dr + \hat{\theta} r d\theta + \hat{\phi} r \sin \theta d\phi$$

New locally orthonormal
unit vectors.

Therefore,

$$|ds|^2 = (dr)^2 + r^2 (d\theta)^2 + r^2 \sin^2 \theta (d\phi)^2$$

$$d^3x = dr (r d\theta) (r \sin \theta d\phi)$$

$$\vec{\nabla} = \hat{r} \frac{\partial}{\partial r} + \frac{\hat{\theta}}{r} \frac{\partial}{\partial \theta} + \frac{\hat{\phi}}{r \sin \theta} \frac{\partial}{\partial \phi}$$

Directions of new unit vectors depend on position and, therefore, on time (when position depends on time).

Unlike Cartesian unit vectors!

F (4)

$$\begin{matrix} \hat{x} & & \hat{y} \\ \hat{\theta} & & \hat{\phi} \end{matrix} \begin{pmatrix} \sin\theta \cos\phi & \sin\theta \sin\phi & \cos\theta \\ +\cos\theta \cos\phi & +\cos\theta \sin\phi & -\sin\theta \\ -\sin\phi & \cos\phi & 0 \end{pmatrix}$$

Matrix of expansion coefficients.

Some work:

$$\vec{\nabla} \times A$$

$$\vec{\nabla}^2 \Phi$$

in spherical coordinates.

Dirac delta fct.:

$$\delta[f(x)] = \sum_i \frac{\delta(x-x_i^0)}{|f'(x_i^0)|}$$

x_i^0 are the simple (!) zeros of $f(x)$.

Matrices:

Inhomogeneous linear eqns:

$$A \vec{x} =$$

F (5)

$$\begin{pmatrix} a_{11} & \dots & a_{12} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{n2} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

Solution for $\Delta = \det |A| \neq 0$.

Cramer's Law:

$$x_k = \frac{\sum_i \Delta_{ik} b_i}{\Delta}, \quad \Delta_{ik} \text{ Co-factors.}$$

Non-Trivial
Homogeneous eqns.:

$$A \vec{x} = 0$$

Solution for $\det |A| = 0$.

Only ratios x_j / x_i determined

(if $x_i \neq 0$) and rank $n-1$.

Add/subtract equations!

Important in QM:

Eigenvalue eqns

$$H v = \lambda \vec{v}, \quad |\vec{v}|^2 = 1$$

$$\det |H - \lambda I_{n \times n}| = 0$$

Characteristic Polynomial

$$\lambda^n + a_{n-1} \lambda^{n-1} + \dots + a_1 \lambda + a_0 = 0$$

Symmetric $\vec{H} = H^{-1}$

\Rightarrow Real solutions.

If $\lambda_i \neq \lambda_j$ for all $i \neq j$

\Rightarrow Eigenvectors \vec{v}_i orthonormal

$$\vec{v}_i \cdot \vec{v}_j = \delta_{ij}$$