

Bayesian Methods: Theory and Practice

Lecture 3.1 – Example Calculations

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May 26, 2009

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Introduction

D0 1995 Top Discovery Data

N = 17 events

b_0 = 3.8 ± 0.6 events

Example Calculations

1. Compute the *p-value*, without and with the background uncertainty.
2. Compute the *posterior density* $p(s|N)$ and its mean and standard deviation.
3. Compute ratio of *evidences* $p(N|H_1)/p(N|H_0)$.

Introduction – Models

Likelihood Functions

$$p(N|b+s, H_1) = \text{Poisson}(N|b+s) = \exp[-(b+s)] (b+s)^N / N!$$

$$p(N|b, H_0) = \text{Poisson}(N|b) = \exp[-b] b^N / N!$$

Prior Density

$$\pi(b, s) = \pi(b|s) \pi(s)$$

$$\pi(b|s) = \pi(b) = \text{Gamma}(kb|B+1) = k \exp(-kb) (kb)^B / \Gamma(B+1)$$

Effective Scale Factor k and Count B

$$b = B / k \qquad B = (b / \delta b)^2 = (3.8 / 0.6)^2 = 41.11$$

$$\delta b = \sqrt{B} / k \qquad k = b / \delta b^2 = 3.8 / 0.6^2 = 10.56$$

Introduction – Integrated Likelihoods

The prior predictive distributions, or **integrated likelihoods**, are

$$\begin{aligned} p(n | s, H_1) &= \int_0^{\infty} \text{Poisson}(n | b + s) \text{Gamma}(kb | B + 1) db \\ &= \left(\frac{k}{1+k} \right)^{B+1} \sum_{r=0}^n \frac{1}{(1+k)^r} \frac{\Gamma(B+1+r)}{\Gamma(B+1)r!} \text{Poisson}(n-r | s) \end{aligned}$$

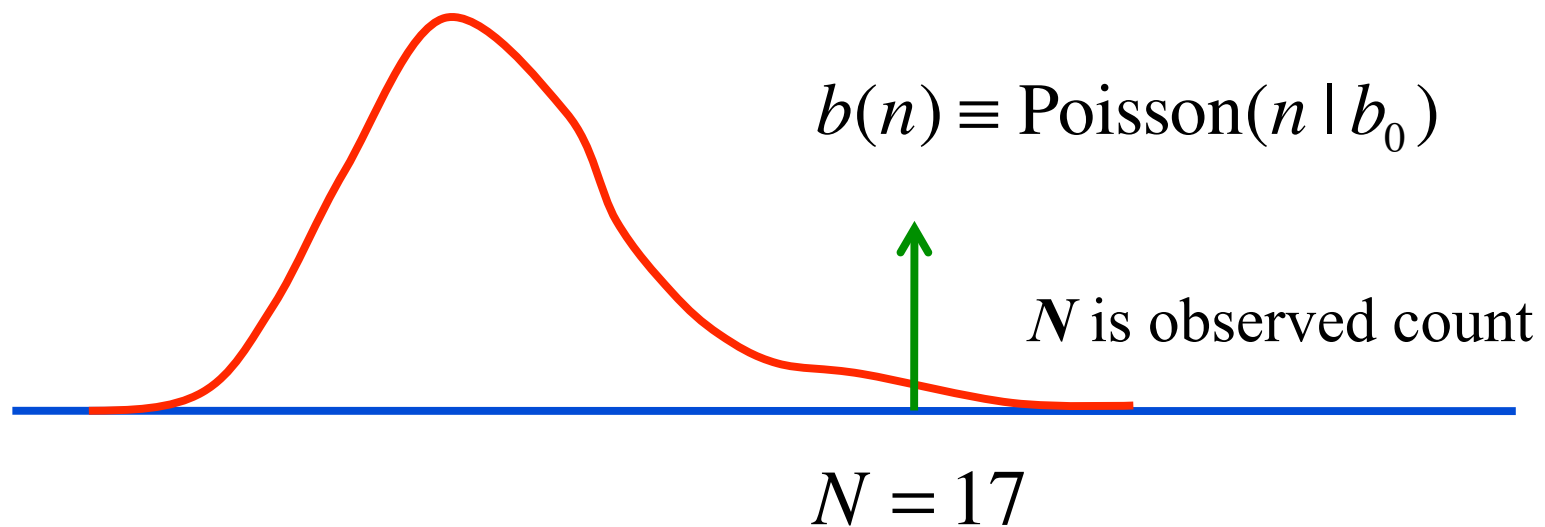
and

$$p(n | H_0) = p(n | s = 0, H_1) = \left(\frac{k}{1+k} \right)^{B+1} \frac{1}{(1+k)^n} \frac{\Gamma(B+1+n)}{\Gamma(B+1)n!}$$

Example Calculations

Example 1: p-value (a)

Background-only, $b_0 = 3.8$ events (ignoring uncertainty)

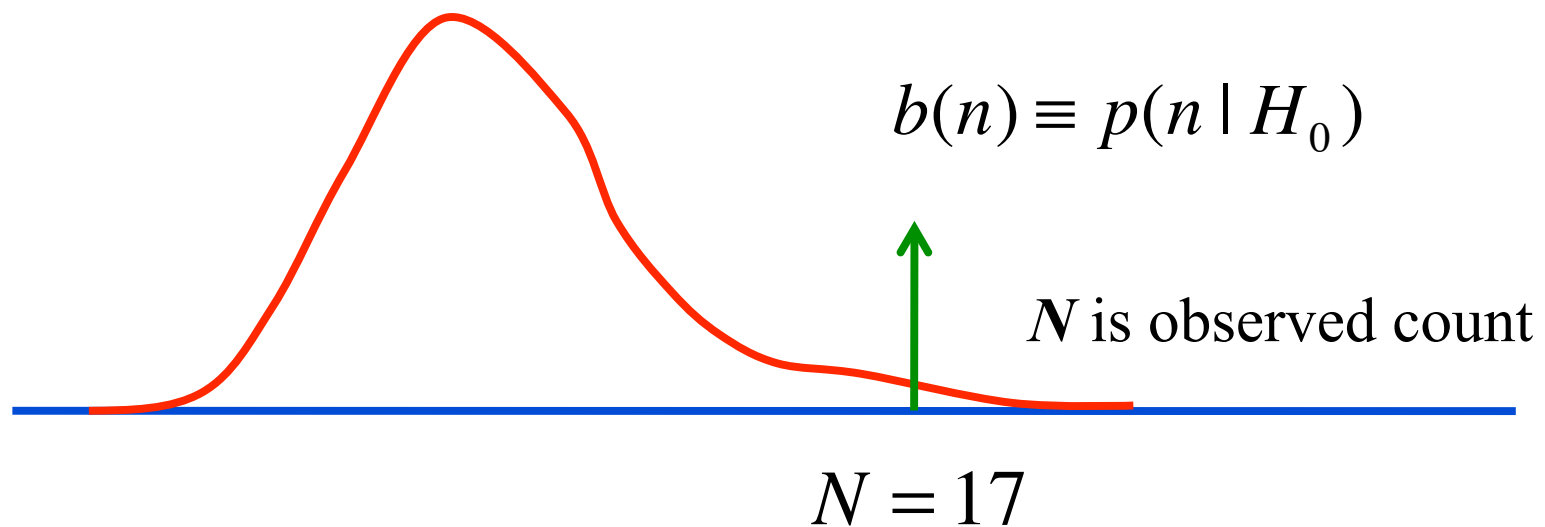


$$p\text{-value} = \sum_{n=N}^{\infty} b(n) = \sum_{n=17}^{\infty} \text{Poisson}(n | 3.8) = 5.7 \times 10^{-7}$$

This is equivalent to 4.9σ

Example 1: p-value (b)

Background-only, $b_0 = 3.8 \pm 0.6$ events



$$p\text{-value} = \sum_{n=N}^{\infty} b(n) = \sum_{n=17}^{\infty} p(n | H_0) = 5.4 \times 10^{-6}$$

This is equivalent to 4.4σ

Example 2: Posterior Density

Given the integrated likelihood

$$p(n | s, H_1) = \left(\frac{k}{1+k} \right)^{B+1} \sum_{r=0}^n c_r(k, B) \text{Poisson}(n-r | s)$$

where

$$c_r(k, B) \equiv \frac{1}{(1+k)^r} \frac{\Gamma(B+1+r)}{\Gamma(B+1)r!}$$

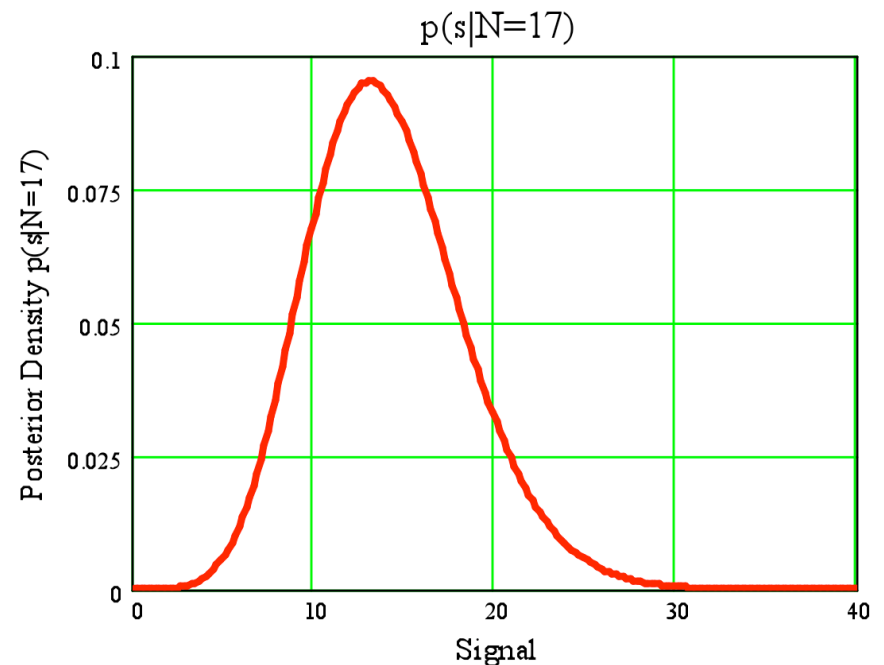
we can compute

$$p(s | n, H_1) = \frac{p(n | s, H_1)\pi(s | H_1)}{\int_0^{\infty} p(n | s, H_1)\pi(s | H_1) ds}$$

Example 2: Posterior Density

Assuming a *flat prior* for the signal $\pi(s|H_1) = \text{constant}$, the posterior density is given by

$$p(s | n) = \frac{\sum_{r=0}^n c_r(k, B) \text{Poisson}(n - r | s)}{\sum_{r=0}^n c_r(k, B)}$$



Example 2: Posterior Density

Next compute the moments of $p(s|n)$ about zero

$$M_m = \int_0^{\infty} s^m p(s|n) ds = \sum_{r=0}^n c_r(k, B) (n-r+m)! / (n-r)! / \sum_{r=0}^n c_r(k, B)$$

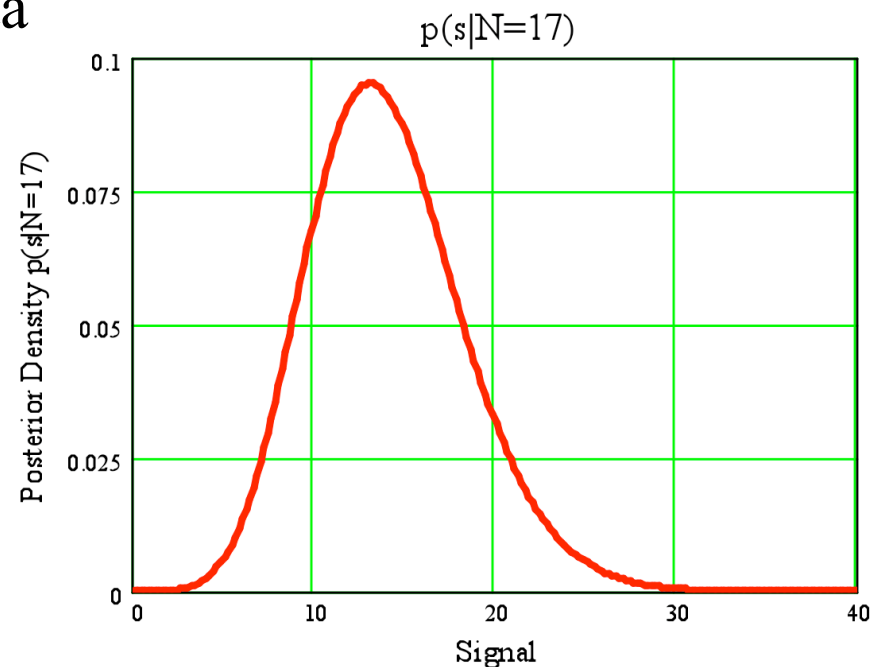
For the top quark discovery data
we find:

mean

$$M_1 = 14.0 \text{ events}$$

standard deviation

$$\sqrt{(M^2 - M_1^2)} = 4.3 \text{ events}$$



Example 3: Evidence

By definition, the evidence for hypothesis H_0 is

$$p(N | H_0)$$

and

$$p(N | H_1) = \int_0^{\infty} p(N | s, H_1) \pi(s | H_1) ds$$

for the alternative hypothesis H_1 . To proceed, we need to specify a *proper* prior for the signal. For simplicity, we shall take the prior to be a delta function at $s = 14$ events.

This yields:

$$\begin{aligned} p(N | H_0) &= 3.86 \times 10^{-6} \\ p(N | H_1) = p(N | s=14, H_1) &= 9.28 \times 10^{-2} \end{aligned}$$

Example 3: Evidence

Since,

$$p(N | H_0) = 3.86 \times 10^{-6}$$

$$p(N | H_1) = 9.28 \times 10^{-2}$$

we conclude that the hypothesis with $s = 14$ events is favored over that with $s = 0$ by **24,000** to **1**.

In terms of a measure akin to “n-sigma,” this is

$$\kappa = \sqrt{2 \ln \left[p(N | H_1) / p(N | H_0) \right]} = 4.5$$

which may be compared with the 4.4σ obtained via the p-value.

Summary

In these examples, we have shown how to

1. Take into account imprecisely known background
2. Estimate the signal and quantify how well this has been done
3. Test the background + signal hypothesis, H_1 , against the background-only hypothesis, H_0 .

The End

“Have the courage to use your *own* understanding!”

Immanuel Kant