

# Simple Harmonic Motion

- Simple harmonic motion is a motion that repeats with time:  $x(t) = A \cos(\omega t + \phi)$
- Mass on a spring:  $\omega = \sqrt{\frac{k}{m}}$
- Simple pendulum:  $\omega = \sqrt{\frac{g}{L}}$ 
  - Also, usually measure position as angle  $\theta(t)$

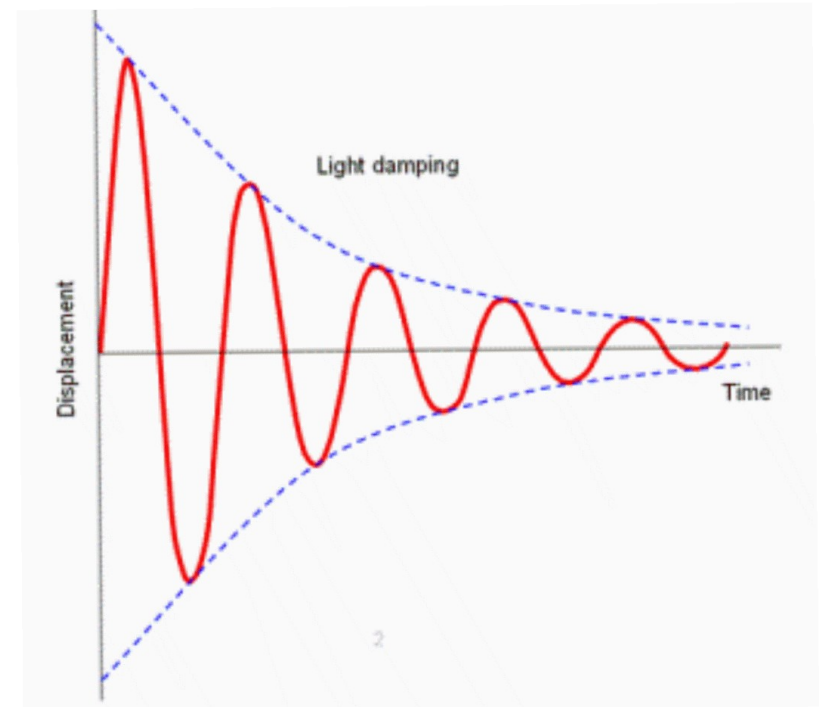
# Damped Harmonic Motion

- If there is an external force removing energy from system, amplitude will go down with time
- If external force proportional to velocity

( $F = -bv$ ):  $x(t) = A e^{-bt/2m} \cos(\omega t + \phi)$

Current amplitude

Original amplitude



# Accelerating Reference Frames (Hint on Pendulum Problems)

- Some problems this homework deal with accelerating reference frames
- We said Newton's 2<sup>nd</sup> only works in non-accelerating frames
- Fix: extra fictitious force to make equations work
- How it changes things for this HW:
  - Instead of weight of objects being  $mg$ , treat force of gravity as  $m(\vec{g} - \vec{a}_{sys})$ 
    - So in equations derived with  $g$ , use magnitude of  $\vec{g} - \vec{a}_{sys}$  instead